Unified parallel encoding and decoding algorithms for Dandelion-like codes

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ABSTRACT

The Dandelion-like codes are eight bijections between labeled trees and strings of node labels. The literature contains optimal sequential algorithms for these bijections, but no parallel algorithms have been reported. In this paper the first parallel encoding and decoding algorithms for Dandelion-like codes are presented. Namely, a unique encoding algorithm and a unique decoding algorithm, which when properly parameterized, can be used for all Dandelion-like codes, are designed. These algorithms are optimal in the sequential setting. The encoding algorithm implementation on an EREW PRAM is optimal, while the efficient implementation of the decoding algorithm requires concurrent reading.

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1. Introduction

Trees are one of the most studied class of graphs in computer science; they are used in a large variety of domains, including computer networks, computational biology, databases, pattern recognition, and web mining. In almost all applications tree nodes and edges are associated with labels, weights, or costs. Examples range from XML data to tree-based dictionaries (heaps, AVL, RB-trees), from phylogenetic trees to spanning trees of communication networks, from indexes to tries (used in compression algorithms). In the literature a range of different representations of tree data structures can be found.

This paper focuses on those representations based on coding labeled trees by means of strings of node labels. It is well known that a naïve method for relating a tree to a string is to associate each node with its parent. Unfortunately, however, the resulting code is not bijective, as an arbitrary string can represent a cyclic and non-connected graph.

At the beginning of the last century, Prüfer [32] showed that it is possible to obtain a one-to-one association between trees and strings, thus providing the first bijective code. Since then many researchers have been fascinated by this topic and have presented a variety of bijective codes. Only in the last two decades, these codes have been used in practical applications.

Bijective codes make it possible to generate random uniformly distributed trees and random connected graphs [13]: the generation of a random string followed by the use of a fast decoding algorithm is typically more efficient than generating a tree by adding edges randomly, since in the latter case one must be careful not to introduce cycles. Furthermore, constraints on the number and on the set of leaves, on the choice of the root, and on the degree of nodes can be easily imposed during the generation.

In XML databases, documents are nested structures often modeled as labeled trees. It is possible to transform XML data into sequences of labels using bijective tree codes. During the query process, search patterns are encoded as sequences as well, thus reducing the problem to substring matching [33]: this allows the total amount of data that needs to be searched during the query process to be reduced.

Genetic algorithms solving problems on trees maintain a population of data structures that represents candidate solutions for a given problem [34]. The association between structures and solutions is realized through a decoder which must exhibit certain desirable properties (like efficiency, locality, and heritability) in order for the evolutionary search to be effective [18].

In network tomography, starting from a matrix of Origin–Destination pair measurements, a researcher may wish to infer the logical network topology. When the network is a tree, it is possible to create a correspondence between the matrix and a string-based representation of the logical network. This leads to a provably correct algorithm for this problem [36].

Other fields of application in which bijective tree codes are used include: fault dictionary storage [2], distributed spanning tree maintenance [20], cryptographic secret sharing [30], and ant-colony optimization heuristics [1].


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Each connected component of a functional digraph is given in Table 1. Costs are expressed as the number of processors multiplied by the maximum time required by a single processor.

### 1. String of node labels

Unless stated otherwise, trees are rooted at node 0 and their nodes are uniquely labeled from 0 to \( n - 1 \).

Cayley's theorem establishes that the number of labeled trees of \( n \) nodes is \( n^{n-2} \) [10], so we consider bijections between such trees and strings over \( \{0, 1, \ldots, n-1\} \) of length \( n - 2 \).

In his proof of Cayley's theorem, Prüfer presented the first bijective string-based code for trees [32]. Many codes behaving like the Prüfer one (i.e., based on recursive leaf elimination) have been introduced: the second and third Neville codes [28] (the first Neville code is analogous to the Prüfer code); Moon's variations of Prüfer's and Neville's codes for rooted trees [27]; the Stack-Queue code due to Deo and Micikevičius [14]. These codes are usually called Prüfer-like codes. We have recently shown [6] that the Chen code [11] also falls into this class.

Other bijective codes with behaviors different from the Prüfer one have also been introduced: the \( \theta_n \) bijection by Eğecioğlu and Remmel [19]; the code due to Kreweras and Moszkowski [25]; the Blob code, the Happy code, and the Dandelion code due to Picciotto [31]; the MHappy code due to Caminiti and Petreschi [7].

#### 1.2. Algorithmic results

Even thought the Prüfer code is dated 1918, to the best of our knowledge, the first linear-time algorithm for encoding a tree appeared only in the late 70's and is due to Klingsberg [24]. The same author also designed an optimal decoding algorithm [17].

A straightforward implementation of the Second Neville code [28] would involve several calls to a sorting routine: this requires \( O(n^2) \) running time using integer sort. Deo and Micikevičius [15] reduced the running time to \( O(n \log n) \) with an encoding algorithm that uses a set of sorted lists. Micikevičius presented the first linear-time algorithm for the Second Neville code [26] while the first optimal decoding algorithm is due to Caminiti et al. [5]. A straightforward implementation of the Third Neville code [28] leads to linear-time algorithms. Deo and Micikevičius introduced the Stack-Queue code [14] with the explicit intent of providing a bijective code with simple linear-time algorithms. Unified optimal encoding and decoding algorithms for these Prüfer-like codes are given by Caminiti et al. [5]. Caminiti and Petreschi presented linear-time algorithms for the Chen code [6].

Among the three codes introduced by Picciotto optimal algorithms were proposed in [31] for just two of them. The first version of optimal algorithms for the Blob code was shown in [7], together with new optimal algorithms for the Happy code and the Dandelion code and the new MHappy code. The \( \theta_n \) bijection is analogous to the Dandelion code and the reinterpretation of the Blob code given in [7] leads to the conclusion that it is identical to the Kreweras and Moszkowski code (see [29]).

A survey on optimal algorithms for bijective codes can be found in [4] while for a deeper dissertation we refer to [3].

Greenlaw, Hallédorsson, and Petreschi [21] presented an optimal EREW PRAM algorithm for Prüfer encoding. It improves an earlier algorithm by Greenlaw and Petreschi [22] and, slightly changed, also works for the third Neville code [5] and for the Chen code [6]. Efficient, but non-optimal, parallel encoding algorithms for the Second Neville code and the Stack-Queue code were presented in [16] and improved in [5]. For the decoding phase, only non-optimal algorithms are known [5]. Recently, parallel algorithms for Blob code have been presented [8]: the encoding algorithm is optimal, while the decoding algorithm requires \( O(n \log n) \) cost (number of processors multiplied by the maximum time required by a single processor) and concurrent read.

To the best of our knowledge no parallel algorithms for other bijective codes have been investigated. Table 1 summarizes the costs of sequential and parallel algorithms for encoding and decoding bijective codes known previously.

This paper is organized as follows: after a few preliminary definitions (Section 2), Section 3 examines a General Scheme defining bijections between trees and strings. Section 4 describes the Dandelion code as originally introduced and reinterprets this code as a transformation of the tree into a functional digraph to map it into the General Scheme. The rest of the paper introduces encoding algorithm and decoding algorithms that, properly parameterized, can be used for all Dandelion-like codes. In Section 5 the class of Dandelion-like codes is defined and the encoding and decoding algorithms are designed. In Section 6 the parallelization of these algorithms on a PRAM is detailed. Conclusions and open problems will follow.

#### 2. Preliminary definitions

In this section, some definitions that will be used in the rest of the paper are reported.

**Definition 1.** Given a function \( g \) from the set \([0, n]\) to the set \([0, n]\), the functional digraph \( G = (V, E) \) associated with \( g \) is a directed graph with \( V = \{0, \ldots, n\} \) and \( E = \{(v, g(v)) \text{ for every } v \in V\} \).

For this class of graphs the following proposition holds:

**Proposition 1.** A digraph \( G = (V, E) \) is a functional digraph if and only if the outer degree of each node is equal to 1.

**Corollary 1.** Each connected component of a functional digraph is composed of several trees, each of which is rooted in a node belonging to the core of the component, which is either a cycle or a loop (see Fig. 1(a)).
Fig. 1. (a) A functional digraph associated with a fully defined function; (b) A functional digraph associated with a function undefined in 0, 8, and 9.

Functional digraphs are easily generalizable for representing functions which are undefined in some values: if $g(x)$ is not defined, node $x$ in $G$ does not have outgoing edges. The connected component of $G$ containing a node $x$ such that $g(x)$ is not defined is a tree rooted at $x$ without cycles or loops (see Fig. 1b). In the following the notation $u \rightarrow v$ is used to identify the unique simple path from node $u$ to node $v$.

Definition 2. A labeled $n$-tree is an unrooted tree with $n$ nodes labeled with distinct values selected in the set $[0, n - 1]$.

Remark 1. Let $T$ be a rooted labeled tree and $p(v)$ be the parent of $v$ for each $v$ in $T$. $T$ is the functional digraph associated with the function $p$.

Definition 3. A code associate trees with strings in such a way that different trees yield different strings. A bijective code is a code associating $n$-trees to $(n - 2)$-strings, where an $n$-string is a string of $n$ elements over the alphabet $[0, n + 1]$.

A naïve method for relating a labeled tree (rooted at node 0) to a string $C$ associates each node $x$ with its parent $p(x)$: $C$ is a string over the alphabet $[0, n - 1]$ whose $i$-th element is $p(i)$. $C$ has cardinality $n - 1$ since node 0 (the root) has no parent and can be omitted. This code is not bijective. Indeed, an arbitrary string of length $n - 1$ over the alphabet $[0, n - 1]$ can represent a cyclic and non-connected graph and consequently does not necessarily correspond to a labeled tree.

This paper deals with bijective codes for labeled trees (simply trees). From now on, all tree edges will be considered as oriented upward from a node to its parent.

Below, when no confusion arises, we will identify a tree with its associated string, and vice versa. We will also consider vectors as functions and vice versa.

3. General scheme

Caminiti and Petreschi [7] defined a General Scheme for bijections between the set of labeled $n$-trees and the set of $(n - 2)$-strings. Here this General Scheme is briefly recalled underlining that the main idea is to modify the naïve method to reduce the length of the string that it yields.

In order to build an $(n - 2)$-string, the tree is rooted at a fixed node $x$, and its topology is manipulated in such a way that there exists another fixed node $y$ having $x$ as parent. When these conditions hold, the information related to both $x$ and $y$ can be omitted from the parent vector, thus obtaining an $(n - 2)$-string.

While it is easy to root a given unrooted tree at a fixed node $x$, it is not clear how to guarantee the existence of edge $(y, x)$.

To this purpose, a function $\varphi$ that manipulates the tree in order to ensure the existence of $(y, x)$ is required. This function must transform $T$ into a functional digraph $G$ associated with a function $g$. The value of $g$ in $x$ must be undefined and $g(y)$ must be equal to $x$. Given $\varphi$, $x$, and $y$ the encoding scheme is as follows:

**Algorithm: General Encoding Scheme**

**Input:** an $n$-tree $T$

**Output:** an $(n - 2)$-string $C$

1. root $T$ in $x$.
2. construct $G = \varphi(T)$.
3. for $v = 0$ to $n - 1$ do
   1. if $v \neq x$ and $v \neq y$ then
      1. add $g(v)$ at the end of $C$.

For the coding to be bijective, the function $\varphi$ must be invertible. Indeed, only under this hypothesis, it is possible to define the decoding scheme:

**Algorithm: General Decoding Scheme**

**Input:** an $(n - 2)$-string $C$

**Output:** an $n$-tree $T$

1. for $v = 0$ to $n - 1$ do
2. if $v \neq x$ and $v \neq y$ then
3. extract the first element $u$ from $C$.
4. $g(v) = u$.
5. reconstruct the functional digraph $G$ associated to $g$.
6. add edge $(y, x)$ to $G$.
7. compute $T = \varphi^{-1}(G)$.

For each node from 0 to $n - 1$ this scheme considers the node’s outgoing edge, so the topology of graph $G$ directly identifies the codeword $C$ that represents $G$. The computational complexities of encoding and decoding schemes strictly depend on the computations of $\varphi$ and $\varphi^{-1}$.

The idea of transforming a tree into a functional digraph was also used in [19,31]. The General Scheme provides a uniform framework that we exploit to design sequential and parallel algorithms for the class of Dandelion-like codes (see Section 5). This class contains the Dandelion code and other known codes, namely, the Happy code, the MHappy code, and the $\vartheta_i$ bijection. Since Dandelion-like codes are defined by modifying the behavior of the Dandelion code, next section is devoted to a detailed description of this code.

4. The Dandelion code

This section examines the Dandelion code as introduced by Picciotto, and reinterprets this code as a transformation of the tree into a functional digraph, in order to map it into the General Scheme.

The poetic name Dandelion derives from the fact that during the encoding all the nodes are connected to node 1 and the resulting tree looks like a dandelion flower (see example in Fig. 2b). During this process, labels on edges are introduced; these labels will be used to create the code. The original encoding algorithm for the Dandelion code is as follows:

**Algorithm: Dandelion Encoding Algorithm**

**Input:** an $n$-tree $T$ rooted in 0 represented by the parent vector $p$

**Output:** an $(n - 2)$-string $C$

1. root $T$ in 0.
2. for $v = n$ downto 2 do
3. $h = p(v)$;
4. $k = p(1)$;
5. remove $(v, h)$;
6. add $(v, 1)$ with label $\text{label}(v, 1) = h$.
7. if a cycle has been created then
8. remove $(1, k)$;
9. add $(1, h)$;
10. $\text{label}(v, 1) = k$.
11. for $v = 2$ to $n$ do
12. $C(v - 2) = \text{label}(v, 1)$.

Analyzing the algorithm, we see that the complexity of the Dandelion Encoding Algorithm is not linear, because it requires testing whether a cycle has been introduced at each iteration. Moreover, for each node $v$ the corresponding value in $C$ is $p(v)$ unless $v$ satisfies the test in Line 7. For this reason we will focus on those nodes that satisfy this test and call them flying nodes.
Lemma 1. Flying nodes are all nodes \( v \) such that:
1. \( v \in 1 \sim 0 \) (excluding 1 and 0) and
2. \( v = \max\{w \in v \sim 0\} \).

Proof. Condition 1 trivially holds, otherwise test of Line 7 cannot be true.

Given \( v \in 1 \sim 0 \) (except 1 and 0), let \( \mu = \max\{w \in v \sim 0\} \). Obviously, \( \mu \) is not smaller than \( v \) since \( v \) belongs to \( v \sim 0 \). Assume that \( v \) is not a flying node but \( \mu > v \), \( \mu \) is processed before \( v \) since nodes are considered by the algorithm in decreasing order. Node \( \mu \) is connected to 1, therefore it introduces a cycle containing \( v \) when the cycle is broken (Lines 8 and 9), all the nodes in the cycle are excluded by the resulting path 1 \( \sim 0 \). This implies that in the following steps \( v \) cannot be a flying node: a contradiction. So if \( v \) is a flying node then \( \mu = v \).

On the other hand, if \( v = \mu \), \( v \) will be in 1 \( \sim 0 \) when it is processed by the algorithm and thus \( v \) introduces a cycle. \( \square \)

When a cycle is broken (Line 8), node 1 is connected to \( h \), the former parent of the flying node \( v \) inducing the cycle, and the label of edge \((v, 1)\) becomes \( k \) (the former parent of 1). In string \( C \), the element corresponding to \( v \) will contain the value \( k \). In order to map the Dandelion code into the General Scheme, it is possible to avoid edge labels and to generate \( C \) directly from vector \( p \) assigning \( p(v) = k \) for each flying node \( v \).

Let us define a function \( \psi \) which, given a tree \( T \), constructs a graph \( G \). \( \psi \) considers flying nodes of \( T \) in decreasing order and swaps \( p(v) \) and \( p(1) \) for each flying node \( v \). We defer an example of the transformation induced by \( \psi \) to the end of this section.

Theorem 1. The Dandelion code fits into the General Scheme when \( x = 0, y = 1 \), and \( \psi = \psi_d \).

Proof. \( G = \psi_d(T) \) is a functional digraph corresponding to a function \( \gamma \) undefined in 0 and such that \( \gamma(1) = 0 \). Lemma 1 guarantees that the code generated using \( \psi_d \) is the same code generated using Dandelion Encoding Algorithm.

Now it is to prove that \( \psi_d \) is invertible, i.e., it is to show how to rebuild \( T \) from \( G \). Flying nodes must be recomputed and all cycles (and loops) in \( G \) must be broken.

Each cycle \( \Gamma \) is identified together with its maximum node \( \gamma \). Clearly \( \gamma \) was a flying node in \( T \), otherwise a node greater than \( \gamma \) would appear in \( \Gamma \).

To invert \( \psi_d \) the outgoing edge of each flying node must be reverted to its original value in \( T \). In order to correctly rebuild the path from 1 to 0, cycles of \( G \) must be considered in increasing order of their maximum node. \( \square \)

From now on, vector \( p \) represents both the parent vector of the input tree and the function associated with the output digraph. The implementation of \( \psi_d \) is as follows:

Algorithm: Compute \( \psi_d \)
Input: an \( n \)-tree \( T \) rooted in 0 represented by the parent vector \( p \)
Output: a functional digraph \( G \) representing a function \( p \)
1. identify all flying nodes \( f_1, f_2, \ldots, f_k \) as ordered in 1 \( \sim 0 \).
2. for \( i = 1 \) to \( k \) do
3. swap \( p(1) \) and \( p(f_i) \).
4. return \( G \) corresponding to \( p \).

Compute \( \psi_d \) requires linear time since Line 1 is a simple backwards scan of the path 1 \( \sim 0 \). So the computation of the Dandelion code, when fitted into the General Scheme, is linear.

The decoding process is more difficult, but still can be done in linear time. Each node \( v \) in \( G \) belongs to a connected component that either contains a cycle or is a simple tree. Let us call \( \gamma \) the maximum node in the cycle of \( v \)’s connected component or the root if the connected component is a tree. The hardest part in the decoding process is the computation of \( \psi_d^{-1} \); it consists in identifying the flying nodes. To this purpose the maximum node that can be reached from \( v \) must be computed, i.e., \( \mu(v) = \max\{p(v) \sim \gamma\} \). This can be done without explicitly identifying \( \gamma \), and without breaking cycles. In order to avoid the risk of infinite recursion on cycles we will associate to each node a variable status to distinguish whether a node is still being processed or not. Initially \( status(v) = \) unprocessed for each node \( v \). The computation of \( \mu(v) \), for all nodes \( v \), is detailed in the algorithm Compute \( \psi_d^{-1} \) given in Box I.

Let us explain the condition of Line 6 in function ComputeMu. Since the status of a node \( v \) is inProgress only during a recursive call on the ascending path of \( v \), when the condition of Line 6 is true a cycle has been identified: following outgoing edges ComputeMu moved from \( v \) back to \( v \) itself. At this point, again, infinite recursions must be avoided: an auxiliary function to compute the maximum in the cycle is called and the recursion terminates.

The auxiliary function MaxInCycle simply scans outgoing edges starting from \( v \) until it reaches \( v \) and returns the maximum label.

Line 17 requires a simple integer sorting; this ensures the linearity of the algorithm for computing \( \psi_d^{-1} \).

An example of \( \psi_d \) and \( \psi_d^{-1} \) concludes this section. Applying Compute \( \psi_d \) to the tree \( T \) in Fig. 2(a) the following flying nodes are identified in the path 1 \( \sim 0 \): \( f_1 = 10 \) and \( f_2 = 5 \). The first iteration of the loop swaps \( p(1) \) with \( p(10) \) obtaining \( p(1) = 2 \) and \( p(10) = 3 \), the second one swaps \( p(1) \) with \( p(5) \) obtaining \( p(1) = 0 \) and \( p(5) = 2 \). The resulting functional digraph \( G \) is shown in Fig. 2(c).

Fig. 2. (a) A sample tree \( T \) rooted in 0; (b) \( T \) after the execution of the Dandelion Encoding Algorithm. (c) The digraph \( G = \psi_d(T) \), flying nodes are depicted in grey.

The Dandelion encoding algorithm fits into the General Scheme when \( \psi_d \) is given in Box I.

When the General Decoding Scheme is used on \( C = (5, 6, 10, 2, 4, 2, 1, 0, 3, 9) \) (with \( x = 0 \) and \( y = 1 \)) a functional digraph equal to \( G \) in Fig. 2(c) is obtained. The procedure Compute \( \psi_d^{-1} \), applied to \( G \) computes the following values: \( \mu(5) = 0, \mu(1) = 0, \mu(2) = 5, \mu(3) = 10, \mu(4) = 10, \mu(5) = 5, \mu(6) = 10, \mu(7) = 5, \mu(8) = 1, \mu(9) = 0, \mu(10) = 10, \mu(11) = 9 \). This implies \( f_1 = 10 \) and \( f_2 = 5 \). Finally the swaps of \( p \) values performed in the encoding are reverted. Then the resulting vector \( p \) describes the original \( T \) as shown in Fig. 2(a).

5. Dandelion-like codes

The class of Dandelion-like codes containing eight bijective codes was introduced in a paper on Genetic Algorithms [29]. In this paper the authors, analyzing the decoding phase of the Dandelion code, underlined that it is possible to introduce four changes into the procedure that builds a tree from a string. Among the sixteen potential codes induced by these four changes, only eight are bijective: the Dandelion-like codes.

In Table 2 these eight codes are described introducing just three changes into the encoding phase, in order to avoid discarding any code. This is a more natural way of describing the class of Dandelion-like codes and the three changes are as follows:
Table 2

<table>
<thead>
<tr>
<th>Code</th>
<th>Max/min</th>
<th>Up/down</th>
<th>Edge orientation</th>
</tr>
</thead>
<tbody>
<tr>
<td>C1</td>
<td>Max</td>
<td>Up</td>
<td>Preserve</td>
</tr>
<tr>
<td>C2</td>
<td>Max</td>
<td>Down</td>
<td>Invert</td>
</tr>
<tr>
<td>C3</td>
<td>Max</td>
<td>Down</td>
<td>Preserve</td>
</tr>
<tr>
<td>C4</td>
<td>Max</td>
<td>Up</td>
<td>Invert</td>
</tr>
<tr>
<td>C5</td>
<td>Min</td>
<td>Up</td>
<td>Preserve</td>
</tr>
<tr>
<td>C6</td>
<td>Min</td>
<td>Down</td>
<td>Invert</td>
</tr>
<tr>
<td>C7</td>
<td>Min</td>
<td>Down</td>
<td>Preserve</td>
</tr>
<tr>
<td>C8</td>
<td>Min</td>
<td>Up</td>
<td>Invert</td>
</tr>
</tbody>
</table>

1. use minimum instead of maximum to compute flying nodes among those nodes in the path 1 ∼ 0;
2. search downward in the path from a node v to the node 1 instead of searching upward in the path v ∼ 0;
3. invert the orientation of all edges in cycles.

As Paulden and Smith observed, C1 is the Dandelion code, C2 is the Happy code, C3 is the MHappy code, and C5 is the \( \varphi_n \) bijection. The following sections introduce parameterized encoding and decoding algorithms suitable for all Dandelion-like codes. We later introduce parallel algorithms for these codes, but sequential versions appear first, in forms that are easy to parallelize though they may appear more complex than necessary.

5.1. Encoding algorithm

We formalize the three parameters required to characterize Dandelion-like codes as follows:

1. \( \mu \in \{ \min, \max \} \) specifies whether to search for minimum or maximum values;
2. \( \| \in \{ \up, \down \} \) establishes if the \( \mu \) values should be searched upward or downward;
3. INVERTEDGES is a boolean value that discriminates whether the orientation of cycle edges should be inverted or not.

For each \( v \) in 1 ∼ 0, the value \( \mu_\| (v) \) represents the maximum/minimum value above/below node \( v \) and \( \text{pred}(v) \) represents the predecessor of \( v \) in the path 1 ∼ 0. Thus, depending on the parameter \( \mu \) and \( \| \), the function \( \mu_\| (v) \) can be one of the followings:

\[
\begin{align*}
\text{max}(v) &= \max\{w \in v \sim 0\} \\
\text{min}(v) &= \min\{w \in v \sim 0\}
\end{align*}
\]

The encoding algorithm is as follows:

Algorithm: Dandelion-Like Encoding Algorithm

Parameters: \( \mu, \|, \text{INVERTEDGES} \)

Input: an n-tree \( T \) rooted in 0 represented by the parent vector \( p \)

Output: a functional digraph \( G \) representing a function \( p \)

1. compute \( \mu_\| (v) \) for each \( v \) in 1 ∼ 0.
2. identify all nodes \( f_1, f_2, \ldots, f_k \) such that \( \mu_\| (f_i) = f_i \) in decreasing order.
3. if \( \| = \down \) do
4. \( f_i = \text{pred}(f_{i+1}) \).
5. for \( i = 1 \) to \( k \) do
6. swap \( p(1) \) and \( p(f_i) \).
7. end
8. end
9. invert edges in all cycles.
10. return \( G \) corresponding to \( p \).

All values \( \mu_\| (v) \) can be computed in \( O(n) \) time with simple forward/backward scans of the path from 1 to 0; at the same time all \( f_i \) are identified. In Line 6, if \( \| = \down \), the highest node below \( f_{i+1} \) is identified, i.e., \( \text{pred}(f_{i+1}) \). Indeed, in this case, \( f_i \) should form a cycle with all nodes above it and below \( f_{i+1} \). This operation can be performed in linear time traversing the path once again. Lines 7–8 intend to rearrange nodes in 1 ∼ 0 into cycles. The overall time complexity is linear since all operations can be accomplished traversing the path 1 ∼ 0 a limited number of times.

We conclude this section by showing the encoding of the tree in Fig. 3 with all Dandelion-like codes. The various codes identify the following nodes in Line 2:

\[
\begin{align*}
C_1, C_4 : f_1 &= 8, f_2 = 3 & C_2, C_3 : f_1 &= 4, f_2 = 6, f_3 = 8 \\
C_5, C_8 : f_1 &= 3 & C_6, C_7 : f_1 &= 4, f_2 = 3
\end{align*}
\]

thus introducing the following cycles in the functional digraph:

\[
\begin{align*}
C_1, C_4 : (4, 6, 8), (3) & C_2, C_3 : (4), (6), (8, 3) \\
C_5, C_8 : (4, 6, 8, 3) & C_6, C_7 : (3, 6, 8, 4).
\end{align*}
\]

The resulting codewords are:
The computation of the reverse function is detailed in Section 5.2. The decoding algorithm identifies all cycles in a given functional digraph and computes, for each cycle $C_i$, the flying node $f_i$ according to the function specified by the parameter $\mu$. Afterward, all cycles are broken and their nodes are placed in between 1 and 0 in such a way that the original path $1 \sim 0$ of the encoded tree is rebuilt. It is to underline that, before breaking cycles, the edge orientation should be reestablished if $\text{invertEdges}$ is true.

To reconstruct the correct order among the flying nodes, the algorithm considers the values of $\mu$ and $\downarrow$. If $\mu = \max$ and $\downarrow = \uparrow$, then the greater $f_i$ must be below any other flying node, thus the $f_i$ values must be ordered in decreasing order: $f_1 > f_2 > \cdots > f_k$. On the other hand, if $\downarrow = \downarrow$ the greater $f_i$ must be placed above any other flying node, thus implying an increasing order: $f_1 < f_2 < \cdots < f_k$. If $\mu = \min$, the orders are reversed. So, the original path $1 \sim 0$ must be rebuilt according to the ordering of the $f_i$ values:

$$1 \sim f_1 \sim f_2 \sim \cdots \sim f_k \sim 0.$$  

Notice that all nodes in $f_i$’s cycle must be placed right above or right below $f_i$, depending on the value of $\downarrow$ (down or up, respectively). The computation of the reverse function is detailed in the Dandelion-Like Decoding Algorithm.

**Algorithm: Dandelion-Like Decoding Algorithm**

**Parameters:** $\mu$, $\downarrow$, $\text{invertEdges}$

**Input:** a functional digraph $G$ representing a function $p$

**Output:** a tree $T$ represented by its parent vector $p$

1. find all cycles $C_i$ and their flying nodes $f_i$ according to $\mu$.
2. if ($\mu = \max$ and $\downarrow = \uparrow$) or ($\mu = \min$ and $\downarrow = \downarrow$) then sort $\{f_i\}$ in decreasing order.
3. else sort $\{f_i\}$ in increasing order.
4. if $\text{invertEdges}$ then
5. invert all edges in cycles.
6. $f_0 = 1$; $f_{k+1} = 0$.
7. if $\downarrow = \downarrow$ then
8. for $i = 1$ to $k$ do
9. $f_i = v_i \in C_i$ such that $p(v_i) = f_i$
10. for $i = k$ downto 1 do
11. swap $p'(i)$ and $p(f_i)$.

Line 1 can be implemented in linear time as done for $\text{compute } \phi^{-1}$. It is to underline that Line 11 (if required) identifies the only node $v_i$ in the cycle of $f_i$ such that $p(v_i) = f_i$: this node becomes the new flying node $f_i$. Since the computations of all $v_i$ can be done in $O(n)$ time, the overall decoding procedure running time remains linear.

### 6. Parallel implementation

In this section the parallel implementation of the encoding and decoding algorithms proposed in Section 5 is detailed for the theoretical PRAM model.

We choose the classical PRAM model because we do not need to address any specific hardware. In the last decade, PRAM model has been deemed useless by many researchers because it is considered too abstract compared with actual parallel architectures. Due to the recent technological advances this trend is changing: Wen and Vishkin reported about the advancements achieved at the University of Maryland within the project PRAM-On-Chip [39]. The XMT (eXplicit Multi-Threading) general-purpose computer architecture is a promising parallel algorithmic architecture to implement PRAM algorithms. They also developed a single-instruction multiple-data (SIMD) multi-thread extension of the C language (with primitives like: Prefix-Sum, Join, Fetch and Increment, etc.) with the intent of providing an easy programming tool for implementing PRAM algorithms. Thus we think that PRAM is robust, reasonable, and well studied theoretical framework for describing high level parallel algorithms. For more information we refer to [37].

In the following some basic parallel techniques used in the parallelization of Dandelion-like encoding and decoding algorithms are listed. Details, proofs, and prerequisites can be found in the literature [12,23,35]. PRAM with Exclusive Write (EW) and both Exclusive Read (ER) and Concurrent Read (CR) are considered.

#### 6.1. Basic parallel techniques

**Scheduling principle:** If a PRAM algorithm $A'$ runs in time $t$ using $p'$ processors, then for any $p'' < p'$, there is an algorithm $A''$ for the same problem and the same PRAM model that runs in time $O(tp'/p'')$ with $p''$ processors.

**Broadcast:** On an EREW PRAM it is possible to broadcast a value $x$, held by a single processor, to all processors in $O(\log n)$ time using $O(n/\log n)$ processors.

**Euler tour:** An Euler tour is a cycle in a directed graph that traverses each edge exactly once. A free tree is converted into a directed
graph by replacing each undirected edge \( u, v \) by two directed edges \( (u, v) \) and \( (v, u) \). An Euler tour of a tree with \( n \) nodes can be computed in \( O(\log n) \) time using \( O(n/\log n) \) processors on an EREW PRAM. The Euler tour can be used to root an unrooted tree and to optimally compute the level of each node.

Let \( \ast \) be an associative binary operation over domain \( \mathcal{D} \) that can be evaluated in \( O(1) \) time using a single EREW PRAM processor.

**Parallel Prefix-Sum:** The **Parallel Prefix-Sum Problem** consists in computing, for all \( j \in [1, n] \), the prefix sums \( S_j = x_1 \ast \cdots \ast x_j \) where \( x_i \in \mathcal{D} \) for \( 1 \leq i \leq n \). The Parallel Prefix-Sum Problem can be solved in \( O(\log n) \) time using \( O(n/\log n) \) processors on an EREW PRAM.

**Parallel tree contraction:** Let \( T_k \) be a regular binary tree with \( n \) nodes (i.e., a tree in which every internal node has exactly two children). Let its leaves be labeled by operands over domain \( \mathcal{D} \) and its internal nodes be labeled by \( \ast \). All the algebraic expressions associated with the internal nodes (one per node) of \( T_k \) can be evaluated in \( O(\log n) \) time using \( O(n/\log n) \) processors on an EREW PRAM.

### 6.2. Parallel encoding

The implementation on an EREW PRAM of the encoding algorithm is the following:

**Algorithm:** **Dandelion-Like Parallel Encoding Algorithm**

**Parameters:** \( \mu \), \( || \), \( \text{invertedEdges} \)

**Input:** a tree \( T \) rooted in 0 represented by its parent vector \( p \)

**Output:** a functional digraph \( G \) representing a function \( p \)

1. **compute** \( \min(T_v) \) and \( \text{level}(v) \) for each \( v \in T \).
2. **create** \( P \) corresponding to the path \( 1 \sim 0 \).
3. **compute** \( \mu_1(v) \) for each \( v \in P \) excluding 1 and 0.
4. **identify** all nodes \( f_1, f_2, \ldots, f_k \) such that \( \mu_1(f_i) = f_i \).
5. \( f_0 = 1; f_k+1 = 0 \).
6. **if** \( || = \text{down} \) **then**
   7. **for** \( i = 1 \) **to** \( k \) **in parallel do**
   8. \( f_i = \text{pred}(f_{i+1}) \).
   9. **for** \( i = 1 \) **to** \( k \) **in parallel do**
   10. \( p(f_i) = p(f_{i-1}) \).
   11. \( p(1) = 0 \).
   12. **if** \( \text{invertedEdges} \) **then**
   13. **for** each \( v \in P \) **in parallel do**
   14. \( \mu(v) = v \).

Initially, the minimum value in the subtree rooted at \( v \), \( \min(T_v) \), is computed for each node \( v \). If \( \min(T_v) = 1 \) then \( v \) is in the path \( 1 \sim 0 \). This operation requires \( O(\log n) \) time with \( O(n/\log n) \) processors by using the Parallel Tree Contraction technique since \( n \) is a binary associative operation. It is to remark that it is always possible to convert a rooted tree \( T \) into a regular binary tree \( T_k \).

The construction replaces every node \( u \) in \( T \) having \( d \) children, \( v_1, v_2, \ldots, v_d \), by \( d + 1 \) nodes \( u^0, u^1, \ldots, u^{d+1} \). In \( T_k \), \( u^i \) is the right child of \( u \). If node \( v_i \) is the \( i \)-th child of \( u \) in \( T \), then \( v_i \) is the left child of \( u^i \) in \( T_k \) (see Fig. 4). This transformation can be obtained in \( O(\log n) \) time using \( O(n/\log n) \) processors on an EREW PRAM [21].

### 6.3. Parallel decoding

The most demanding step in the parallel decoding algorithm is the computation of flying nodes. These nodes can be identified in \( O(\log n) \) time with \( O(n) \) processors on a CREW PRAM in a Pointer Jumping like fashion: for each node the outgoing edge is followed searching for the max/min value in the ascending path (the parameter \( \mu \) discriminates whether to search for maximum or minimum values). After each step we set \( p(v) = p(p(v)) \), thus obtaining a single Pointer Jump. The procedure is as follows:

**Algorithm:** **Parallel Identification of Flying Nodes**

1. \( p(0) = 0 \).
2. **for each node \( v \in T \) in parallel do**
3. \( \text{asc}(v) = v \).
4. \( \text{self}(v) = \text{true} \).
5. **for** \( j = 1 \) **to** \( \log n \) **do**
6. **for each node \( v \in T \) in parallel do**
7. **if** \( \text{asc}(p(v)) = \mu(\text{asc}(p(v)), \text{asc}(u)) \) **then**
8. \( \text{asc}(v) = \text{asc}(p(v)) \).
9. \( \text{self}(v) = \text{false} \).
10. \( p(v) = p(p(v)) \).

The value \( \text{asc}(v) \) is the min/max value in the ascending path of \( v \). At each step \( \text{asc}(v) \) is compared with \( \text{asc}(p(v)) \) and updated, if it is the case. Notice that the algorithm explicitly flag whether the value \( \text{asc}(v) \) comes from \( v \) itself or has been encountered in the proper ascending path. At the end of the \( \log n \) iterations if \( \text{asc}(v) = v \) and \( \text{self}(v) = \text{false} \) then \( v \) is the min/max node in its cycle. Indeed, a value equal to \( v \) has been found in the proper ascending path of \( v \), this means that there exists a path \( v \sim v \), i.e., a cycle. Moreover, no node smaller/greater than \( v \) has been encountered in this cycle. All these nodes can be enumerated with Prefix-Sum to generate the (increasing or decreasing) ordered sequence of the flying nodes \( f_1, f_2, \ldots, f_k \). A copy of \( p \) should be used in the **Parallel Identification of Flying Nodes**, since the original vector \( p \) will be required latter in the decoding.

Once flying nodes have been identified, a Broadcast operation can be used to propagate a flag in their ascending paths, thus identifying all nodes belonging to any cycle. The decoding algorithm proceeds as follows:
Table 3
Costs of known and new algorithms for bijective string-based codes. Costs of parallel algorithms are expressed as the number of processors multiplied by the maximum time required by a single processor. Algorithms marked with CR require concurrent read, while all other algorithms work on an EREW PRAM.

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>Encoding</th>
<th>Decoding</th>
<th>Parallel Encoding</th>
<th>Decoding</th>
</tr>
</thead>
<tbody>
<tr>
<td>Prüfer</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>2nd Neville</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>3rd Neville</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>Stack-Queue</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>Chen</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>Dandelion</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>αβ bijection</td>
<td>O(n log n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>Happy</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>MHappy</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
<tr>
<td>Blob</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n)</td>
<td>O(n log n)</td>
</tr>
</tbody>
</table>

All the three loops in Lines 3, 7, and 9 require O(1) time with O(n) processors on an EREW PRAM, provided that the \( \text{pred} \) values are computed for all nodes belonging to any cycle (as described in the parallel encoding for nodes in \( P \)). The overall cost of Dandelion-Like Parallel Decoding Algorithm on a CREW PRAM is \( O(n \log n) \), due to the bottleneck of this algorithm that is the Parallel Identification of Flying Nodes.

7. Conclusions and open problems

This paper presents what, to the best of our knowledge, are the first encoding and decoding parallel algorithms for the Dandelion-like codes. A unique encoding algorithm and a unique decoding algorithm have been designed which, properly parameterized, can be used for all eight codes. These algorithms, optimal in the sequential setting, have been implemented on the classical PRAM model.

The encoding algorithm has been parallelized using an EREW PRAM with \( O(n/\log n) \) processors and requires \( O(\log n) \) time: the overall cost is consequently linear and the algorithm is optimal. Concerning Prüfer-like codes, we remark that for the Second Neville code and for the Stack-Queue code parallel encoding is not optimal: a bottleneck arises from the use of an integer sorting algorithm. This bottleneck is avoided for Dandelion-like codes since all the sorting requirements are accomplished with simple Prefix-Sum computations.

The decoding algorithm can be efficiently parallelized on a CREW PRAM to run in \( O(\log n) \) time with \( O(n) \) processors: the overall cost is \( O(n \log n) \). The only non-optimal step of the parallel implementation is the computation of characteristic nodes in cycles realized in a Pointer Jumping like fashion. It does not seem possible to avoid this step, but it remains an open problem to understand if this computation can be achieved with linear cost. Table 3 completes Table 1 with the results presented in this paper. Observing these results it is clear that the problem of designing optimal parallel algorithms is still open for several codes. In particular no optimal decoding algorithm is known: the best decoding algorithms cost \( O(n\sqrt{\log n}) \) on an EREW PRAM. It remains an interesting open problem to design a bijective code that admits an optimal parallel decoding algorithm, or to show that such a result cannot be achieved by providing a lower bound to the parallel cost of decoding.

References


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