I/O Management and Disk Scheduling

Chapter 11

Categories of I/O Devices

- Human readable– Printers, Display, Keyboard etc.
 - Used to communicate with the user
- Machine readable
 Disk and tape drives, Sensors, Controllers, Actuators
 - Used to communicate with electronic equipment
- Communication– Digital line drivers
 - Used to communicate with remote devices

Differences in I/O Devices

- Data rate (several orders of magnitude)
- Application (file management sw, virtual mem. management sw and hw, different priorities-terminal)
- Complexity of control
- Unit of transfer (byte steam for terminal vs large blocks for disk)
- Data representation- different encoding schemes
- Error conditions respond differently to errors

Performing I/O: Types

- Programmed I/O-- Process is busy-waiting for the operation to complete
- Interrupt-driven I/O
 - I/O command is issued
 - Processor continues executing instructions
 - I/O module sends an interrupt when done
- Direct Memory Access (DMA)
 - DMA controls exchange of data between main memory and the I/O device
 - Processor interrupted only after entire block has been transferred

Evolution of the I/O Function

- Processor directly controls a peripheral device
- Controller or I/O module is added
 - Processor uses programmed I/O without interrupts
 - Processor does not need to handle details of external devices

Evolution of the I/O Function

- Controller or I/O module with interrupts
 - Processor does not spend time waiting for an I/O operation to be performed
- Direct Memory Access
 - Blocks of data are moved into memory without involving the processor
 - Processor involved at beginning and end only

Evolution of the I/O Function

- I/O module is a separate processor
- I/O processor
 - I/O module has its own local memory
 - Its a computer in its own right

Direct Memory Access

- Processor delegates I/O operation to the DMA module
- DMA module transfers data directly to or form memory
- When complete DMA module sends an interrupt signal to the processor

DMA Configurations



(a) Single-bus, detached DMA



(b) Single-bus, Integrated DMA-I/O

DMA Configurations



Figure 11.3 Alternative DMA Configurations

Operating System Design Issues

- Efficiency
 - Most I/O devices extremely slow compared to main memory
 - Use of multiprogramming allows for some processes to be waiting on I/O while another process executes
 - I/O cannot keep up with processor speed
 - Swapping is used to bring in additional Ready processes which is an I/O operation

I/O Buffering

- Reasons for buffering
 - Processes must wait for I/O to complete before proceeding
 - Process cannot be entirely swapped outcorresponding pages must remain in main memory during I/O
 - Risk of single process deadlock
 – process swapped out before I/O operation starts

I/O Buffering

- Block-oriented
 - Information is stored in fixed sized blocks
 - Transfers are made a block at a time
 - Used for disks and tapes
- Stream-oriented
 - Transfer information as a stream of bytes
 - Used for terminals, printers, communication ports, mouse and other pointing devices, and most other devices that are not secondary storage

Single Buffer

- OS assigns a buffer in MM for an I/O request
- Block-oriented
 - Input transfers made to buffer
 - Block moved to user space when needed
 - Another block is moved into the buffer (read ahead)



Single Buffer

- Block-oriented
 - User process can process one block of data while next block is read in
 - Swapping can occur since input is taking place in system memory, not user memory
 - Operating system keeps track of assignment of system buffers to user processes

Single Buffer

- Stream-oriented
 - Used a line-at-a-time, e.g. line printer (or byteat-a-time, e.g., form-mode terminals)
 - Output to the terminal is one line at a time

Double Buffer

- Use two system buffers instead of one
- A process can transfer data to or from one buffer while the operating system empties or fills the other buffer



(c) Double buffering

Circular Buffer

- More than two buffers are used
- Each individual buffer is one unit in a circular buffer
- Used when I/O operation must keep up with process



(d) Circular buffering

Disk Performance Parameters

- R/W: find track and sector and position the head
- Seek time
 - Time it takes to position the head at the desired track
- Rotational delay or rotational latency
 - Time its takes for the beginning of the sector to reach the head



Disk Performance Parameters

- Access time
 - Sum of seek time and rotational delay
 - The time it takes to get in position to read or write
- Data transfer occurs as the sector moves under the head

- Seek time is the reason for differences in performance
- For a single disk there will be a number of I/O requests
- If requests are selected randomly, we will have poor performance

- First-in, first-out (FIFO)
 - Process request sequentially
 - Fair to all processes
 - Approaches random scheduling in performance if there are many processes

- Priority
 - Goal is not to optimize disk use but to meet other objectives
 - Short batch jobs may have higher priority
 - Provide good interactive response time

- Last-in, first-out
 - Good for transaction processing systems
 - The device is given to the most recent user so there should be little arm movement
 - Possibility of starvation since a job may never regain the head of the line

- Shortest Service Time First
 - Select the disk I/O request that requires the least movement of the disk arm from its current position
 - Always choose the minimum Seek time
 - Problem: Always coming in nearby requests

- SCAN (elevator)
 - Arm moves in one direction only, satisfying all outstanding requests until it reaches the last track in that direction
 - Direction is reversed
 - Max latency: 2t
- C-SCAN
 - Restricts scanning to one direction only
 - When the last track has been visited in one direction, the arm is returned to the opposite end of the disk and the scan begins again
 - Max latency: t + seek_time
 - Arm stickiness!

- N-step-SCAN
 - Disk requests divided into subqueues of length N
 - Subqueues are processed one at a time, using SCAN
 - New requests added to other queue when queue is processed
 - Big N →SCAN; N=1 → FIFO
- FSCAN
 - Two queues
 - One queue is empty for new requests

Disk Cache

- Buffer in main memory for disk sectors
- Contains a copy of some of the sectors on the disk

Disk Cache: Design issues

- 1) Deliver the data from cache to process
 - a) Transfer the data from cache to process
 - b) Use shared memory capability and pass pointers (readers/writers model)
- 2) Replacement strategy: Which block to replace?

Least Recently Used

- Cache = Stack of blocks
- When a block is referenced or brought into the cache, it is placed on the top of the stack
- Replace the last block in the cache
- Blocks are not moved around:
 - Stack of pointers

Least Frequently Used

- A counter is associated with each block
- Counter is incremented each time block accessed
- Replace block with smallest count (fewest references)
- Counter misleading: blocks referenced many times in short periods

Frequency Based Replacement

- Two-section stack-like organization
- A counter is associated with each block
- The counter is incremented only when block goes from old section to new one
- Replace the old-section block with smallest counter
- Problem: New Section blocks do not have enough time to increment counter



Frequency Based Replacement

- Three-section stack-like organization
- A counter is associated with each block
- Counter changes for middle-section and old-section blocks
- Replace the old-section block with smallest counter
- The middle-section allows blocks to increment their counter before falling down to the old section



(b) Use of three sections

Replacement

- On-demand
 - Replace sector only when need the slot
 - Does not cluster writes
- Pre-planned
 - Release a number of slots each time
 - Good for clustering writes